

4. (d) The question asks whether there exist scalars a , b , and c so that $\begin{bmatrix} 5 \\ 3 \\ 4 \end{bmatrix} = a \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} +$

$$b \begin{bmatrix} 2 \\ 3 \\ 2 \end{bmatrix} + c \begin{bmatrix} -4 \\ 5 \\ -1 \end{bmatrix}. \text{ For this, we would need } \begin{matrix} 2a + 4b - 4c = 5 \\ 3b + 5c = 3 \\ a + 2b - c = 4 \end{matrix}. \text{ This system has}$$

the solution $a = -\frac{5}{4}$, $b = \frac{9}{4}$, $c = -\frac{3}{4}$, so the answer is "yes". The given vector is in the column space of the matrix.

- (e) The question asks whether there exist scalars a and b so that $\begin{bmatrix} -4 \\ -6 \\ 1 \\ 0 \end{bmatrix} = a \begin{bmatrix} -1 \\ -5 \\ -4 \\ 2 \end{bmatrix} + b \begin{bmatrix} 2 \\ 3 \\ 9 \\ 4 \end{bmatrix}.$

For this, we would need $-a + 2b = -4$, $-5a + 3b = -6$, $-4a + 9b = 1$, and $2a + 4b = 0$. There are no solutions, so the answer is no. The given vector is not in the column space.

5. (c) In general, with $b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$, we again attempt to solve $Ax = b$ for $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$. Gaussian

elimination applied to the augmented matrix proceeds

$$\begin{aligned} \left[\begin{array}{ccc|c} 2 & -1 & 4 & b_1 \\ 0 & 2 & 3 & b_2 \\ -1 & -5 & 1 & b_3 \\ 1 & -3 & 2 & b_4 \end{array} \right] &\rightarrow \left[\begin{array}{ccc|c} 1 & -3 & 2 & b_4 \\ 0 & 2 & 3 & b_2 \\ 0 & 5 & 0 & b_1 - 2b_4 \\ 0 & -8 & 3 & b_3 + b_4 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & -3 & 2 & b_4 \\ 0 & 1 & \frac{3}{2} & \frac{1}{2}b_2 \\ 0 & 5 & 0 & b_1 - 2b_4 \\ 0 & -8 & 3 & b_3 + b_4 \end{array} \right] \\ &\rightarrow \left[\begin{array}{ccc|c} 1 & -3 & 2 & b_4 \\ 0 & 1 & \frac{3}{2} & \frac{1}{2}b_2 \\ 0 & 0 & -\frac{15}{2} & b_1 - 2b_4 - \frac{5}{2}b_2 \\ 0 & 0 & 15 & b_3 + b_4 + 4b_2 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & -3 & 2 & b_4 \\ 0 & 1 & \frac{3}{2} & \frac{1}{2}b_2 \\ 0 & 0 & 15 & -2b_1 + 4b_4 + 5b_2 \\ 0 & 0 & 15 & b_3 + b_4 + 4b_2 \end{array} \right]. \end{aligned}$$

Thus b is in the column space if and only if

$$-2b_1 + 4b_4 + 5b_2 = b_3 + b_4 + 4b_2; \quad (1)$$

that is, if and only if $2b_1 - b_2 + b_3 - 3b_4 = 0$. Here's why. If (1) is not true, the last two lines in our final matrix contradict each other and there is no solution to $Ax = b$. On the other hand, if (1) holds, then one more step in the Gaussian elimination makes the final row zero and we can solve for x_3 , x_2 , and x_1 by back substitution, just as in part (b).

8. (c) $\left[\begin{array}{cccc} 1 & 2 & 3 & 5 \\ 1 & 0 & 1 & 3 \\ 2 & 3 & 5 & 9 \end{array} \right] \rightarrow \left[\begin{array}{cccc} 1 & 2 & 3 & 5 \\ 0 & -2 & -2 & -2 \\ 0 & -1 & -1 & -1 \end{array} \right] \rightarrow \left[\begin{array}{cccc} 1 & 2 & 3 & 5 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$

There are two pivots, so the rank is 2.

10. (a) The null space is the set of solutions to $Ax = 0$.

$$\left[\begin{array}{ccc} 1 & 0 & 3 \\ 3 & 1 & 16 \\ 5 & 2 & 29 \end{array} \right] \rightarrow \left[\begin{array}{ccc} 1 & 0 & 3 \\ 0 & 1 & 7 \\ 0 & 2 & 14 \end{array} \right] \rightarrow \left[\begin{array}{ccc} 1 & 0 & 3 \\ 0 & 1 & 7 \\ 0 & 0 & 0 \end{array} \right].$$

Thus $x_3 = t$ is free, $x_2 + 7x_3 = 0$, so $x_2 = -7x_3 = -7t$ and $x_1 + 32x_3 = 0$, so $x_1 = -32x_3 = -32t$. The null space is all vectors of the form $\begin{bmatrix} -32t \\ -7t \\ t \end{bmatrix} = t \begin{bmatrix} -32 \\ -7 \\ 1 \end{bmatrix}.$

- (b) The rank of A is the number of pivot columns. From part (a), we see $\text{rank } A = 2$.

$$(c) \left[\begin{array}{ccc|c} 1 & 0 & 3 & 2 \\ 3 & 1 & 16 & 3 \\ 5 & 2 & 29 & 4 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 3 & 2 \\ 0 & 1 & 7 & -3 \\ 0 & 2 & 14 & -6 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 3 & 2 \\ 0 & 1 & 7 & -3 \\ 0 & 0 & 0 & 0 \end{array} \right]. \text{ Thus } x_3 = t \text{ is free,}$$

$$x_2 + 7x_3 = -3, \text{ so } x_2 = -3 - 7t \text{ and } x_1 + 3x_3 = 2, \text{ so } x_1 = 2 - 3t. \text{ The solution is}$$

$$\mathbf{x} = \begin{bmatrix} 2 - 3t \\ -3 - 7t \\ t \end{bmatrix} = \begin{bmatrix} 2 \\ -3 \\ 0 \end{bmatrix} + t \begin{bmatrix} -3 \\ -7 \\ 1 \end{bmatrix}.$$

(d) From part (c), we see that one particular solution to $A\mathbf{x} = \mathbf{b}$ is $\begin{bmatrix} 2 \\ -3 \\ 0 \end{bmatrix}$, so $\mathbf{b} = \begin{bmatrix} 2 \\ -3 \\ -6 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} - 3 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$. (Many other solutions are possible.)

11. (a) [BB] Since $A\mathbf{x} = 0$, $(BA)\mathbf{x} = B(A\mathbf{x}) = B\mathbf{0} = 0$, so \mathbf{x} is in the null space of BA .
 (b) Since \mathbf{x} is the column space of A , $\mathbf{x} = A\mathbf{y}$ for some vector \mathbf{y} . Thus $\mathbf{x} = (BC)\mathbf{y} = B(C\mathbf{y})$ so \mathbf{x} is in the column space of B .

4.2

1. (c) Any linear combination of $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ will have third component 0. So \mathbf{v} is **not** a linear combination of $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$.

2. (c) The question is whether there are scalars a, b and c so that $\mathbf{v} = a\mathbf{v}_1 + b\mathbf{v}_2 + c\mathbf{v}_3$.

This is $A\mathbf{x} = \mathbf{v}$ with $A = \begin{bmatrix} 0 & 3 & 2 \\ -1 & 0 & 1 \\ 1 & 0 & -1 \\ 2 & -1 & 1 \end{bmatrix}$ and $\mathbf{x} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$. Gaussian elimination on the

augmented matrix proceeds

$$\left[\begin{array}{ccc|c} 0 & 3 & 2 & 1 \\ -1 & 0 & 1 & -1 \\ 1 & 0 & -1 & 1 \\ 2 & -1 & 1 & 9 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 1 \\ 0 & 3 & 2 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 3 & 7 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 1 \\ 0 & 1 & -3 & -7 \\ 0 & 0 & 11 & 22 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 1 \\ 0 & 1 & -3 & -7 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right].$$

The system has the solution $c = 2, b = -1, a = 3$, so $\mathbf{v} = 3\mathbf{v}_1 - \mathbf{v}_2 + 2\mathbf{v}_3$ is in the span of $\mathbf{v}_1, \mathbf{v}_2$ and \mathbf{v}_3 .

- (d) The question is whether there are scalars a, b and c so that $\mathbf{v} = a\mathbf{v}_1 + b\mathbf{v}_2 + c\mathbf{v}_3$.

This is $A\mathbf{x} = \mathbf{v}$ with $A = \begin{bmatrix} 0 & 3 & 2 \\ -1 & 0 & 1 \\ 1 & 0 & -1 \\ 2 & -1 & 1 \end{bmatrix}$ and $\mathbf{x} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$. Gaussian elimination on the

augmented matrix proceeds

$$\left[\begin{array}{ccc|c} 0 & 3 & 2 & 2 \\ -1 & 0 & 1 & 0 \\ 1 & 0 & -1 & 1 \\ 2 & -1 & 1 & -3 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 1 \\ 0 & 3 & 2 & 2 \\ 0 & 0 & 0 & 1 \\ 0 & -1 & 3 & -3 \end{array} \right].$$

The third equation reads $0 = 1$. There is no solution. Vector \mathbf{v} is **not** in the span of the others.

4. (a) These vectors do not span \mathbb{R}^3 . The span of two nonparallel vectors in \mathbb{R}^3 is a plane. To find the equation of this plane (not required, but a good student will find it anyway), we write $au_1 + bu_2 = \begin{bmatrix} 2a + 6b \\ a \\ -3a + b \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$. Solving the first equations for a and b gives $a = y$ and $x = 2a + 6b = 2y + 6b$, so $b = \frac{1}{6}(x - 2y)$. Then $z = -3a + b = -3y + \frac{1}{6}(x - 2y)$, so $x - 20y - 6z = 0$.

(b) These vectors do span \mathbb{R}^3 . Let $\mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ be any vector in \mathbb{R}^3 . We claim that there are

scalars c_1, c_2 and c_3 so that $\mathbf{x} = c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + c_3\mathbf{u}_3$. In matrix form, this is $\mathbf{x} = A \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$,

where $A = \begin{bmatrix} 2 & 6 & 1 \\ 1 & 0 & 1 \\ -3 & 1 & 1 \end{bmatrix}$. Since $\det A = -25 \neq 0$, A is invertible, so $\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = A^{-1}\mathbf{x}$.

7. (c) U is not a subspace since it is not closed under addition: for example, $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$

are in U , but their sum $\begin{bmatrix} 1 \\ 1 \\ 4 \end{bmatrix}$ is not because $4 \neq 1 + 1 + 1$.

(There are other possible answers. For instance, U is not closed under scalar multiplication. Also, U does not contain the zero vector.)

(e) This is not a subspace of \mathbb{R}^3 because it is not closed under scalar multiplication: For example, $\mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ is in U , but $\frac{1}{2}\mathbf{x}$ is not in U .

10. (b) The question is whether there are scalars c_1, c_2, c_3 , not all 0, such that $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 = \mathbf{0}$. This is $A\mathbf{c} = \mathbf{0}$, with $A = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 1 & 4 \\ 3 & -1 & 11 \end{bmatrix}$ and $\mathbf{c} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$. Gaussian elimination

proceeds $\begin{bmatrix} 1 & 1 & -1 \\ 2 & 1 & 4 \\ 3 & -1 & 11 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 \\ 0 & -3 & 6 \\ 0 & -7 & 14 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$.

There are many nontrivial solutions, for example, $c_1 = -3, c_2 = 2, c_3 = 1$ (hence $-3\mathbf{v}_1 + 2\mathbf{v}_2 + \mathbf{v}_3 = \mathbf{0}$), so the vectors are linearly dependent.

(c) The question is whether there are scalars c_1, c_2, c_3 , not all 0, such that $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 = \mathbf{0}$. This is $A\mathbf{c} = \mathbf{0}$, with $A = \begin{bmatrix} -2 & 3 & 2 \\ 3 & 4 & 1 \\ 3 & 0 & 1 \\ 1 & 7 & 3 \end{bmatrix}$ and $\mathbf{c} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$. Gaussian elimination

proceeds $\begin{bmatrix} -2 & 3 & 2 \\ 3 & 4 & 1 \\ 3 & 0 & 1 \\ 1 & 7 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 7 & 3 \\ 0 & 17 & 8 \\ 0 & -17 & -8 \\ 0 & -21 & -8 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 7 & 3 \\ 0 & 17 & 8 \\ 0 & 21 & 8 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 7 & 3 \\ 0 & 1 & \frac{8}{17} \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$. The solution

is $c_1 = c_2 = c_3 = 0$, so the vectors are linearly independent.