

Pathspace Connections and 2-Groups

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1 Motivation

Throughout these notes, a fixed local trivialization of all principal bundles is assumed. This allows us to simplify some calculations by dealing with \mathfrak{g} -valued k -forms and G -valued functions directly.

1.1 Fundamental Theorem of Calculus

Let us first recall why electromagnetism is easy:

Lemma 1.1. (*Poincaré, Gauss, Leibniz, ...*) *There is an exact sequence of sheaves*

$$1 \longrightarrow \underline{U(1)} \xrightarrow{C} C^\infty(X, U(1)) \xrightarrow{d \log} \Omega_X^1(i\mathbb{R}) \xrightarrow{d} \Omega_X^2(i\mathbb{R}) \xrightarrow{d} \Omega_X^3(i\mathbb{R}) \xrightarrow{d} \dots$$

where $\underline{U(1)}$ is the sheaf of locally constant functions.

In particular, if we are given a 2-form $F \in \Omega_X^2(i\mathbb{R})$, we know that F locally comes from a potential $A \in \Omega^1$ if and only if $dF = 0$. This means we can easily test which 2-forms could be electromagnetic fields, and finding a potential is no more difficult than finding an antiderivative.

For more general Yang-Mills gauge fields, the group $U(1)$ will be replaced with a nonabelian group G . In this case, we at least have

Lemma 1.2. (*Cartan?*) *There is an exact sequence of sheaves*

$$1 \longrightarrow \underline{G} \xrightarrow{C} C^\infty(X, G) \xrightarrow{* \theta} \Omega_X^1(\mathfrak{g}) \xrightarrow{\text{curv}} \Omega_X^2(\mathfrak{g})$$

where $*\theta : f \mapsto f^{-1} \cdot df$ and $\text{curv } \omega = d\omega + \omega \wedge \omega$.

Unfortunately, the obvious necessary condition for $F \in \Omega^2(\mathfrak{g})$ to satisfy $\text{curv } \omega = F$ for some $\omega \in \Omega^1(\mathfrak{g})$ is the Bianchi identity

$$0 = d^\omega F = dF + \omega \wedge F$$

which explicitly depends on already having the gauge potential ω on hand.

1.2 From Space to Pathspace

Let $\tilde{\mathcal{P}}X$ denote the space of $[0, 1]$ -parametrized, piecewise smooth paths in X . Similarly, let $\mathcal{P}X$ be the space of unparametrized (but oriented) piecewise smooth paths in X .

It is natural to ask what the fundamental theorem of calculus looks like from the perspective of pathspace. If $\omega \in \Omega_X^1(i\mathbb{R})$ is given, then we can get a function $P : \mathcal{P}X \rightarrow U(1)$ by

$$P(\gamma) = \exp\left(\int_{\gamma} \omega\right)$$

Likewise, a k -form $\eta \in \Omega_X^k(i\mathbb{R})$ gives a $(k-1)$ -form $\tau(\eta) \in \Omega_{\mathcal{P}X}^{k-1}(i\mathbb{R})$ by the formula

$$\tau(\eta)_{\gamma}(v_1, \dots, v_{k-1}) = \int_0^1 \eta(v_1(t), \dots, v_{k-1}(t), \gamma'(t)) dt$$

where the v_i are vectorfields along γ (that is, tangent vectors to $\mathcal{P}X$ at γ). Note that this formula does not depend on the parametrization of γ .

The above discussion can be summarized by this suggestive diagram, where $G = U(1)$, Ω^k means $\Omega^k(\mathfrak{g})$, and C_X^∞ means $C^\infty(X, G)$:

$$\begin{array}{ccccccccccc} 1 & \longrightarrow & \underline{G} & \longrightarrow & C_X^\infty & \xrightarrow{d \log} & \Omega_X^1 & \xrightarrow{d} & \Omega_X^2 & \xrightarrow{d} & \Omega_X^3 & \xrightarrow{d} & \dots \\ & & \downarrow & & \downarrow i & & \downarrow \exp f & & \downarrow \tau & & \downarrow \tau & & \\ & & 1 & \longrightarrow & \underline{G}_{\mathcal{P}} & \longrightarrow & C_{\mathcal{P}X}^\infty & \xrightarrow{D \log} & \Omega_{\mathcal{P}X}^1 & \xrightarrow{D} & \Omega_{\mathcal{P}X}^2 & \xrightarrow{D} & \dots \end{array}$$

Here, $\underline{G}_{\mathcal{P}}$ means “functions on pathspace which only depend on the endpoints”.¹

Lemma 1.3. *Everything in this diagram commutes.*

Proof. First, we need to explain the map $D : \Omega_{\mathcal{P}X}^k \rightarrow \Omega_{\mathcal{P}X}^{k+1}$. This is essentially the exterior derivative on pathspace, with a corrective factor thrown in for the motion of the endpoints. Explicitly, if $\omega \in \Omega_{\mathcal{P}X}^k(i\mathbb{R})$ is given and we choose a curve γ , then there is some k -form $\hat{\omega}$ such that

$$\omega_{\gamma}(v_1, \dots, v_k) = \int_0^1 \hat{\omega}_{\gamma(t)}(v_1(t), \dots, v_k(t)) dt$$

Now we define

$$(D\omega)_{\gamma}(v_0, \dots, v_k) = (d\omega)_{\gamma}(v_0, \dots, v_k) + \widehat{d\omega}_{\gamma(0)}(v_0(0), \dots, v_k(0)) - \widehat{d\omega}_{\gamma(1)}(v_0(1), \dots, v_k(1))$$

¹Although this definition may seem *ad hoc*, it is motivated by thinking of the pathspace $\mathcal{P}X$ as a sort of smooth category.

Let us just prove that the square

$$\begin{array}{ccc} \Omega_X^1 & \xrightarrow{d} & \Omega_X^2 \\ \downarrow \exp f & & \downarrow \tau \\ C_{\mathcal{P}X}^\infty & \xrightarrow{D \log} & \Omega_{\mathcal{P}X}^1 \end{array}$$

commutes, the general case being just a messier version of this. Starting with an arbitrary $\omega \in \Omega_X^1$, write

$$\omega = \sum_{i=1}^n \omega_i dx^i, \quad d\omega = \frac{1}{2} \sum_{i,j=1}^n \left(\frac{\partial \omega_j}{\partial x^i} - \frac{\partial \omega_i}{\partial x^j} \right) dx^i \wedge dx^j$$

Now pick a curve γ and a vectorfield $v = v^i \partial/\partial x^i$ along it. Without (much) loss of generality, assume that γ' is linearly dependent on $\partial/\partial x^1$. Then we have

$$\begin{aligned} \tau(d\omega)_\gamma(v) &= \int_0^1 d\omega_{\gamma(t)}(v(t), \gamma'(t)) dt \\ &= \sum_{i=1}^n \int_0^1 \left(\frac{\partial \omega_1}{\partial x^i} - \frac{\partial \omega_i}{\partial x_1} \right) \cdot v^i \cdot \gamma' dt \\ &= \int_0^1 \partial_v \omega_1 \cdot \gamma' dt - \sum_{i=1}^n \int_0^1 \frac{d\omega_i}{dt} \cdot v^i dt \\ &= \int_0^1 \partial_v \omega_1 \cdot \gamma' + \omega \left(\frac{dv}{dt} \right) dt + \omega_{\gamma(0)}(v(0)) - \omega_{\gamma(1)}(v(1)) \end{aligned}$$

On the other hand, we can compute $d \int \omega$ and add in boundary terms to find $D \log \exp \int \omega$. By looking at terms of order ϵ when perturbing γ to $\gamma + \epsilon v$, we find that

$$\begin{aligned} \partial_v \int_\gamma \omega &= \int_0^1 \partial_{v(t)} \omega_{\gamma(t)}(\gamma'(t)) + \omega_{\gamma(t)}(v'(t)) dt \\ &= \int_0^1 \partial_v \omega_1 \cdot \gamma' + \omega \left(\frac{dv}{dt} \right) dt \end{aligned}$$

Adding in the boundary terms, we find $D \log \exp \int \omega = \tau d\omega$, as advertised. \square

In words, this lemma means we can lower the degree of our forms by moving to pathspace. The primordial example of this is the equivalence between connections (approximately 1-forms on X) and parallel transport operators (approximately functions on $\mathcal{P}X$).

In a perfect world, we could hope that there is some general relationship between 2-forms F on X and connection 1-forms B on $\mathcal{P}X$. The curvature 2-form $dB + B \wedge B$ on $\mathcal{P}X$ would be related to some 3-form back on X . The vanishing of this 3-form would then be equivalent to the Bianchi identity.

Unfortunately, things aren't quite so nice. The field copy problem prevents us from constructing a map $\Omega_X^2(\mathfrak{g}) \xrightarrow{\tau} \Omega_{\mathcal{P}X}^1(\mathfrak{g})$ in the nonabelian case. The rest of this paper demonstrates a possible resolution to this problem. The trick is to look at degree 2 “forms” with coefficients in a so-called 2-group. These 2-groups remember enough information to let us really construct a map from such objects to $\Omega_{\mathcal{P}X}^1$ in exact analogy with the abelian τ .

1.3 From Pathspace back to Space

Without going into any details, let us just remark that there is a map ϵ which takes “nice enough” k -forms on $\mathcal{P}X$ and gives us $(k+1)$ -forms on X . ϵ works by evaluating the k -form on an infinitesimally short path to get a $(k+1)$ -form. Antisymmetry follows from parametrization independence.

2 Connections on Pathspace

2.1 Smooth Functions versus Smooth Functors on $\mathcal{P}X$

If G is any Lie group and ω a \mathfrak{g} -valued 1-form on X and $\gamma : [0, 1] \rightarrow X$ a path, we can form the path-ordered product

$$\exp \int_{\gamma} \omega \stackrel{\text{def}}{=} \lim_{N \rightarrow \infty} \prod_{k=1}^N \exp \left\{ \frac{1}{N} \cdot \omega_{\gamma(k/N)} (\gamma'(k/N)) \right\}$$

This gives the map $\Omega_X^1(\mathfrak{g}) \rightarrow C^\infty(\mathcal{P}X, G)$ which takes a connection to its parallel transport operator. But not every smooth function F on $\mathcal{P}X$ is a parallel transport — F must be functorial², in the sense that

$$F(\beta \circ \alpha) = F(\beta) \cdot F(\alpha)$$

We are therefore only interested in smooth *functors* from $\mathcal{P}X$ to G , since these are the only sort of thing which may arise from a connection on X . In other words, we are not interested in *functions* on $\mathcal{P}X$ since they do not respect the extra structure of pathspace. On the other hand, *functors* respect the underlying composition structure.

²If we treat the group G as a category with one object and all arrows invertible.

What is the infinitesimal version of this functorality? Define

$$B = F^*\theta = F^{-1} \cdot dF$$

and let v be a vectorfield on γ . Now subdivide $\gamma = \beta \circ \alpha$, splitting v into a vectorfield x on α and y on β . For shorthand, we will write $v = y \circ x$. Now if F is functorial,

$$d(F_{\beta \circ \alpha})(y \circ x) = dF_{\beta}(y) \cdot F_{\alpha} + F_{\beta} \cdot dF_{\alpha}(x)$$

so we have

$$\begin{aligned} B_{\gamma}(v) = B_{\beta \circ \alpha}(y \circ x) &= F_{\beta \circ \alpha}^{-1} \cdot dF_{\beta \circ \alpha}(y \circ x) \\ &= F_{\alpha}^{-1} \cdot F_{\beta}^{-1} dF_{\beta}(y) \cdot F_{\alpha} + F_{\alpha}^{-1} dF_{\alpha}(x) \\ &= B_{\alpha}(x) + \text{Ad}(F_{\alpha}^{-1})(B_{\beta}(y)) \end{aligned}$$

Of course, an arbitrary 1-form ω on $\mathcal{P}X$ will not have this property — there will generally be no relationship between ω_{α} , ω_{β} and $\omega_{\beta \circ \alpha}$ ³. We want our connections to have this infinitesimal functorality so that parallel transport gives a *functor* instead of merely a *function*. This means we need to restrict somewhat our naïve notion of connection on pathspace. To ensure functorality, we must have

$$B_{\beta \circ \alpha}(y \circ x) = B_{\alpha}(x) + \alpha(A_{\alpha})(B_{\beta}(y))$$

where A is some functor with values in H and α is an action of H on \mathfrak{g} .

This leads us to define the connection in two parts:

Definition 2.1. Let G, H be Lie groups equipped with an action

$$H \xrightarrow{\alpha} \text{Aut}(G)$$

A $(\mathfrak{g}, \mathfrak{h})$ -connection on $\mathcal{P}X$ is a pair (B, A) with

$$\begin{aligned} B &\in \Omega_{\mathcal{P}X}^2(\mathfrak{g}) \\ A &\in \Omega_{\mathcal{P}X}^1(\mathfrak{h}) \end{aligned}$$

³It is interesting to note that if an arbitrary 1-form ω on $\mathcal{P}X$ satisfies

$$d\omega + \omega \wedge \omega = 0$$

then it automatically is infinitesimally functorial, since the antiderivative P satisfies

$$P^{-1}dP_{\beta \circ \alpha} = P^{-1}dP_{\alpha} + \text{Ad}(P_{\alpha}^{-1})(P^{-1}dP_{\beta})$$

This is why the problem of functorality never appears in *A Poincaré Lemma for Connection Forms*.

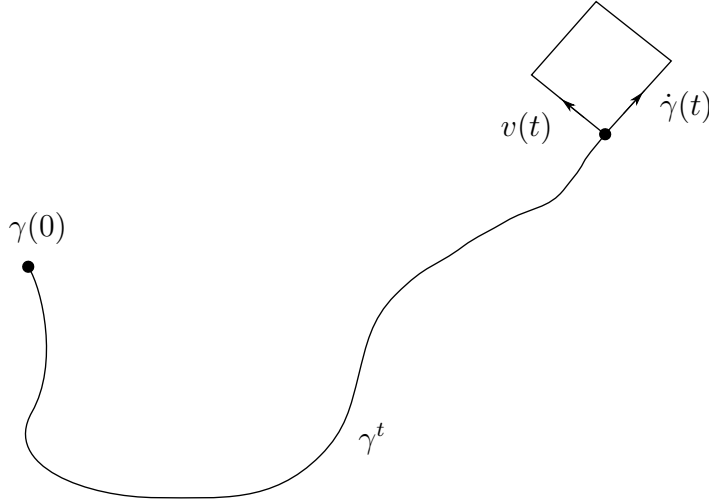


Figure 1: Schematic depiction of $B_{\gamma(t)}(v(t), \dot{\gamma}(t))^{\exp \int_{\gamma^t} A}$

Given a $(\mathfrak{g}, \mathfrak{h})$ -connection, we can construct a \mathfrak{g} -valued 1-form ω on $\mathcal{P}X$ by

$$\omega_\gamma(v) \stackrel{\text{def}}{=} \int_0^1 B_{\gamma(t)}(v(t), \dot{\gamma}(t))^{\exp \int_{\gamma^t} A} dt$$

where the superscript represents the action of H on \mathfrak{g} and $\gamma^t(\tau) = \gamma(t\tau)$. The ω constructed in this way has the property that

$$\omega_{\beta \circ \alpha} = \omega_\alpha + (\omega_\beta)^{g_\alpha}$$

for some element $g_\alpha \in H$ acting on \mathfrak{g} and depending functorially on α . In other words, ω is infinitesimally functorial. It is not difficult to see that every infinitesimally functorial connection comes from such a construction.

Example 2.1. The motivating example comes from choosing $G = H$ with the adjoint action. Then a $(\mathfrak{g}, \mathfrak{h})$ -connection is given by $B \in \Omega_X^2(\mathfrak{g})$, $A \in \Omega_X^1(\mathfrak{g})$. The connection on pathspace is

$$\omega_\gamma(v) = \int_0^1 P_{\gamma^t} \cdot B(v(t), \dot{\gamma}(t)) \cdot P_{\gamma^t}^{-1} dt$$

where

$$P_{\gamma^t} = \exp \int_{\gamma^t} A$$

By construction, ω satisfies

$$\omega_{\beta \circ \alpha} = \omega_\alpha + (\omega_\beta)^{P_\alpha}$$

Direct calculation shows that if $B + dA + A \wedge A = 0$ then the curvature $d\omega + \omega \wedge \omega$ vanishes.

2.2 2-Groups

The data (G, H, α) is almost the defining data for a strict 2-group, which is a group with both “horizontal” and “vertical” multiplication (though the vertical operation is only partially-defined, like composition).

Definition 2.2. A (*strict*) 2-group is a quadruple $\mathbf{G} = (G, H, t, \alpha)$ where G and H are groups,

$$H \xrightarrow{\alpha} \text{Aut}(G)$$

an action of H on G and

$$G \xrightarrow{t} H$$

a homomorphism. t and α must be compatible in the following two ways: t must intertwine α with the adjoint action on H

$$\begin{array}{ccc} G & \xrightarrow{\alpha_h} & G \\ t \downarrow & & \downarrow t \\ H & \xrightarrow{\text{Ad}(h)} & H \end{array}$$

and the Peiffer identity

$$\begin{array}{ccc} G & & \\ \downarrow t & \searrow \text{Ad} & \\ H & \xrightarrow{\alpha} & \text{Aut}(G) \end{array}$$

must hold.

Given a 2-group, we can form the *group of arrows* $G \rtimes_{\alpha} H$. This group has the usual horizontal product

$$(g_2, h_2) \cdot (g_1, h_1) = (g_2 \cdot \alpha(h_2)(g_1), h_2 h_1)$$

but also a vertical product: whenever $h_2 = t(g_1) \cdot h_1$ we can define

$$(g_2, t(g_1)h_1) \circ (g_1, h_1) = (g_2 g_1, h_1)$$

A 2-connection will assign an infinitesimal group element in $\mathfrak{g} \rtimes \mathfrak{h}$ to each bit of surface by assigning an element of \mathfrak{h} to line elements (the “starting point”) and an element of \mathfrak{g} to surface elements (the “motion along the surface”).

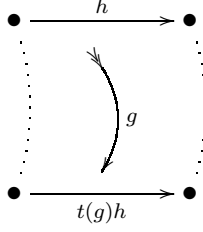


Figure 2: $(g, h) \in \mathfrak{g} \rtimes \mathfrak{h}$ Acting on a Surface Element

Definition 2.3. A 2-connection η on X for the 2-group $\mathbf{G} = (G, H, t, \alpha)$ is given by a 2-form $B \in \Omega_X^2(\mathfrak{g})$ and a 1-form $A \in \Omega_X^1(\mathfrak{h})$. The *curvature* of η is the 3-form

$$d^A B = dB + A \wedge_{d\alpha} B \in \Omega_X^3(\mathfrak{g})$$

where the wedge product is defined using the action $d\alpha$ of \mathfrak{h} on \mathfrak{g} . The *fake curvature* of η is the 2-form

$$dA + A \wedge A + t(B) \in \Omega_X^2(\mathfrak{h})$$

Every 2-connection on X determines a \mathfrak{g} -valued connection ω on $\mathcal{P}X$ by

$$\omega_\gamma(v) = \int_0^1 \alpha(\exp \int_{\gamma^t} A) (B(v(t), \gamma'(t))) dt$$

Once we have a 2-connection, we can compute surface-ordered products!

Definition 2.4. Let $\eta = (B, A)$ be a 2-connection for \mathbf{G} as above, and let ω be the associated \mathfrak{g} -valued connection on $\mathcal{P}X$. Then to any curve Γ in $\mathcal{P}X$ (that is, a parametrized surface in X) we can associate the *surface-ordered product*

$$\exp \iint_{\Gamma} \eta \stackrel{def}{=} \exp \int_{\Gamma} \omega$$

There are other curves Γ' in $\mathcal{P}X$ corresponding to the same surface S in X . If (and only if) the fake curvature of η vanishes, a theorem of Baez and Schreiber shows that

$$\exp \iint_{\Gamma} \eta = \exp \iint_{\Gamma'} \eta$$

so we can define the surface-ordered product

$$\exp \iint_S \eta$$

without worrying about which parametrization of S is chosen.